Joel Cabrera

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Enviolence
MSc in Engineering: Computer Science, 2024 - 2026 Télécom Paris - Palaiseau, France
 Computer Science, Machine Learning, Artificial Intelligence, Image Processing.
 France's top-ranked school for computer science and digital technology.
 B.Eng.: Computer Engineering, 2021 - 2026 Universidad De La República (UdelaR) - Montevideo, Uruguay Data Structures and Algorithms, Programming, Computer Networks, Operating Systems, Software Engineering, Database Management, and Linux systems.
 Experience with software development methodologies and collaborative projects.
WORK HISTORY —
Research Assistant, 03/2024 - 08/2024 Facultad De Ingeniería, UdelaR - Montevideo, Uruguay • Assistant on robotics-related research projects.
 Reviewed and synthesized scientific literature in English, effectively summarizing complex concepts and clearly communicating findings to supervisors.
 Enhanced critical thinking and adaptability by overcoming language barriers and rapidly assimilating technical content in robotics research.
Research Collaborator, 07/2022 - 12/2022 Facultad De Ingeniería, UdelaR - Montevideo, Uruguay • Developed Arduino-based prototype enhancing math learning for children, boosting engagement and understanding. • Added data tracking features, providing actionable insights for educators.
• Integrated sensors, actuators, and Python tools for seamless hardware-software interaction.
 Tested with 200 six-year-olds, showing improved engagement and comprehension.
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• Technical: Python, C/C++, Java, Prolog, JavaScript, HTML5, CSS, PostgreSQL, Arduino, ROS (Robot Operating System).
• Languages: Spanish native speaker, fluent in English and French.
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• Excellence Scholarship for Master's Studies 2024 Awarded by the National Agency for Research and Innovation (ANII), Campus France, and the French Embassy in

Uruguay.

• Best Team Spirit – Robocup Junior | 2020

Recognized for outstanding teamwork and collaboration in the international robotics competition.

- 1st Place SUMO.uy Competition (Basic Category) | 2020
 - Secured first place in a robotics challenge involving line-following, object collection, and obstacle avoidance tasks.
- 1st Place National Robotics and Programming Olympiad (Plan Ceibal) | 2020 Developed and presented a prototype guide designed to assist athletes with low vision.